

Text Generation by Offline Reinforcement Learning

He He



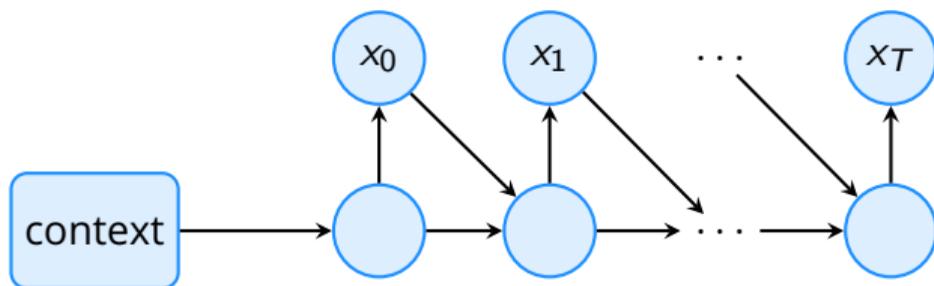
NEW YORK UNIVERSITY

Tsinghua University, IIS, RL Reading Group

May 31, 2022

The status quo for text generation

- **Modeling:** Auto-regressive models



$$p(\text{output} \mid \text{context}) = \prod_t p(t\text{-th word} \mid \text{prefix}, \text{context})$$

The status quo for text generation

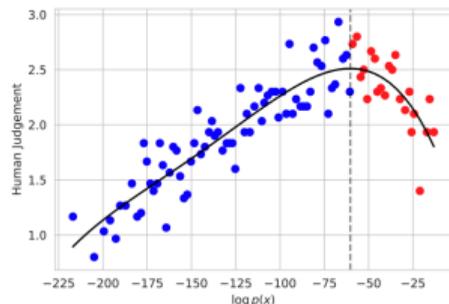
- ▶ **Learning:** Maximum likelihood estimation

$$\max_{\theta} \sum_{\text{reference}} \log p_{\theta}(\text{reference} \mid \text{context})$$

- ▶ **Inference:** focus on the **high-likelihood** region
 - ▶ **Search** for the highest-likelihood output:
greedy decoding, beam search
 - ▶ **Sample** from the learned distribution:
top- p , top- k , tempered sampling

Likelihood vs quality

High log-likelihood $\not\Rightarrow$ high quality



[Zhang+ 2020]

A: How about watching a movie?

B: I don't know.

A: Let's go home then.

B: I don't know.

[Li+ 2016]

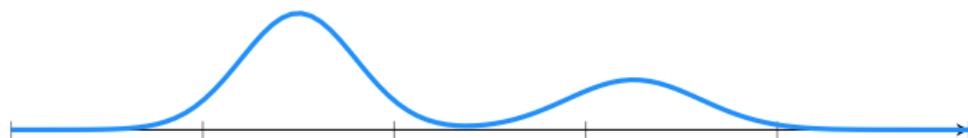
beam-1: British woman won Olympic gold in pair rowing.

beam-1000: </s>

[Murray+ 2018, Ott+ 2018]

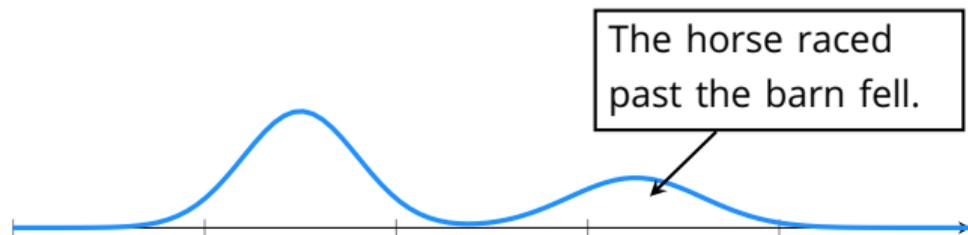
What does the model error look like?

MLE tends to **over-generalize** [Huszar 2015]



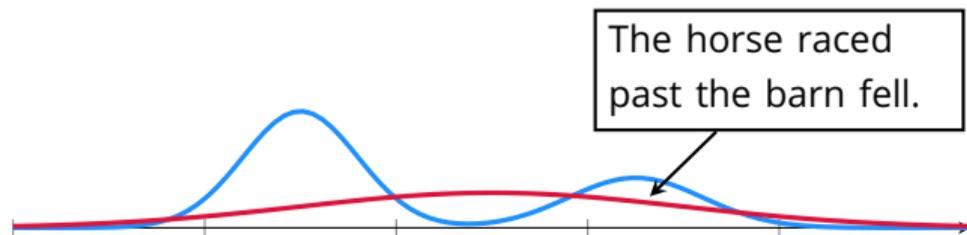
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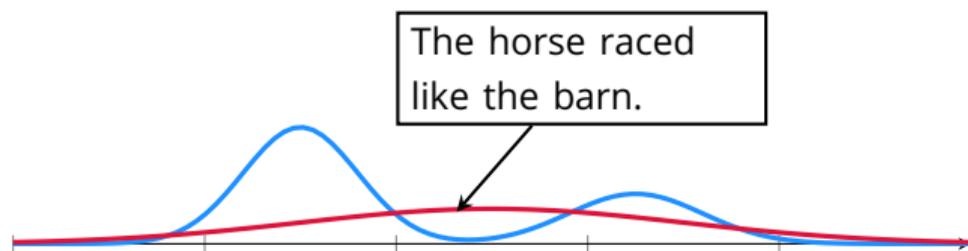
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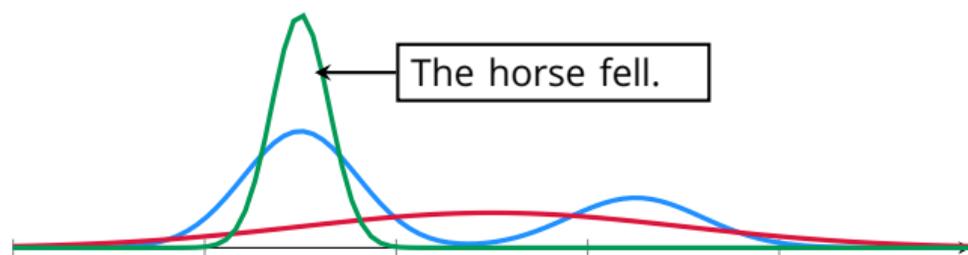
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MLE is "high recall",

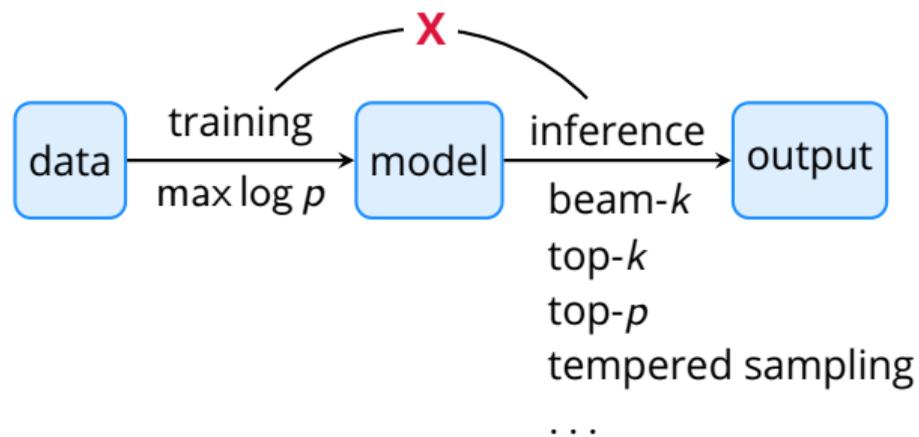
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MLE is "high recall", but a "high precision" solution may be preferred.

Misaligned training and evaluation objectives



log-likelihood of the reference text



quality of the output text (judged by humans)

Contents

Training vs evaluation losses

Training loss (NLL):

$$\mathbb{E}_{p_{\text{human}}} [-\log p_{\theta}(\text{output} \mid \text{context})]$$

Evaluation loss (perceptual quality):

$$\mathbb{E}_{p_{\theta}} [-\log p_{\text{human}}(\text{output} \mid \text{context})]$$

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Training vs evaluation losses

Training loss (NLL):

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- ▶ High recall: p_{θ} must cover all **outputs** from p_{human}

Evaluation loss (perceptual quality):

$$\mathbb{E}_{p_{\theta}} [-\log p_{\text{human}}(\text{output} \mid \text{context})]$$

- ▶ High precision: all **output** from p_{θ} must be scored high under p_{human}

The reinforcement learning formulation

Evaluation loss (perceptual quality):

$$-\mathbb{E}_{p_{\theta}} \left[\sum_t \log p_{\text{human}}(t\text{-th word} \mid \text{prefix, context}) \right]$$

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The RL objective: expected return

$$J(\theta) = \mathbb{E}_{\pi_{\theta}} \left[\sum_t R(a_t, s_t) \right]$$

Aligned training and evaluation losses

Existing RL approaches for text generation

Directly optimize a **sequence-level metric** (reward), e.g., BLEU, ROUGE, using policy gradient.

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- ▶ Aligned training and evaluation goals
- ▶ May discover high-quality outputs outside the references.

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Cons:

```
we have the the the the the ...  
i to me to me to me to me ...
```

degenerative solution

Optimization challenges

Obstacles:

- ▶ Gradient estimated by samples from π_θ has high variance.
- ▶ Degenerate once the reward is close to zero.

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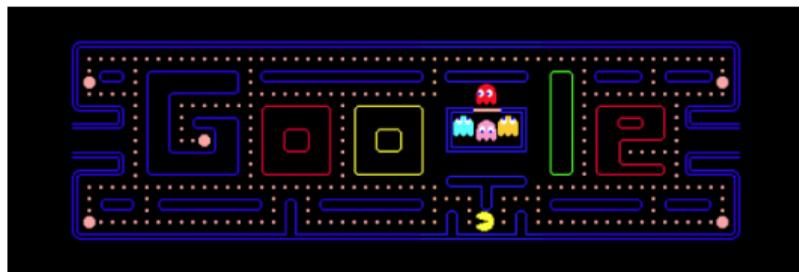
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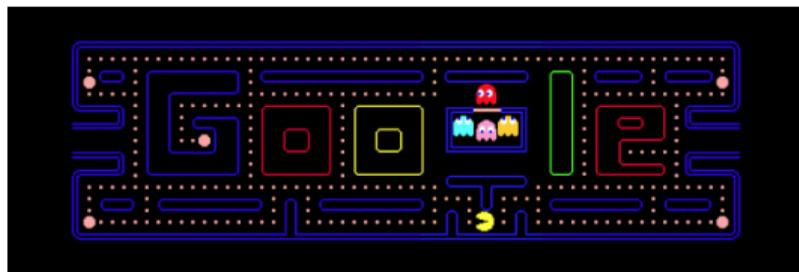
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Problem: policy/generator *interacting* with the environment.

Is interaction useful?

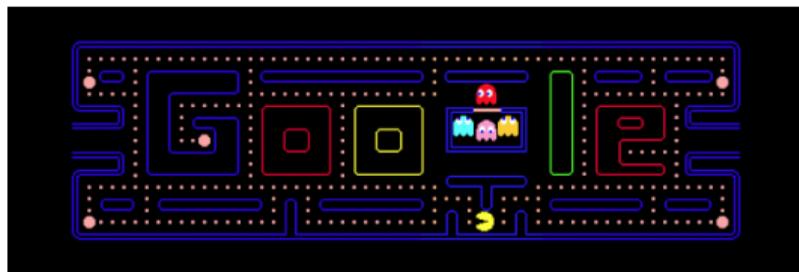


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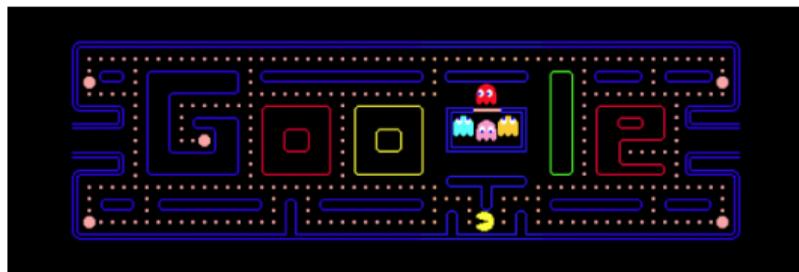
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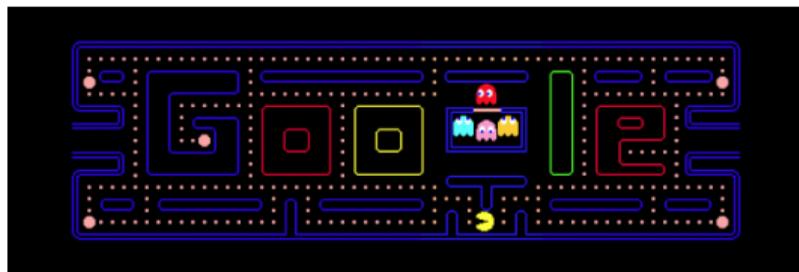
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- ▶ Learn about the environment dynamics.
 - ▶ We already know the dynamics.
- ▶ Explore novel actions that may lead to higher reward.
 - ▶ We don't have good reward functions (evaluation) yet.

Summary so far

Desired loss:

$$-\mathbb{E}_{p_\theta} \log p_{\text{human}}(\text{output} \mid \text{context})$$

(high precision)

Existing approaches:

- ▶ MLE: **misaligned** losses, **easy** to optimize
- ▶ RL: **aligned** losses, **hard** to optimize

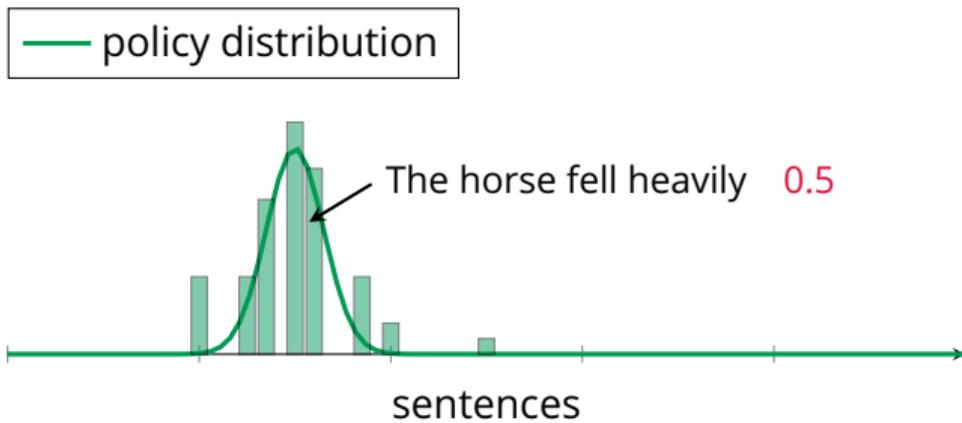
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Online policy gradient

Objective: $\mathbb{E}_{\pi_{\theta}} [R(s, a)]$

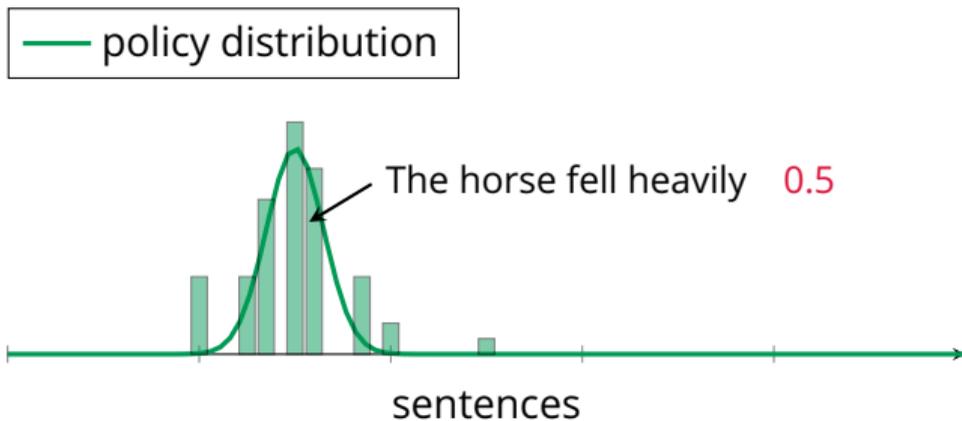
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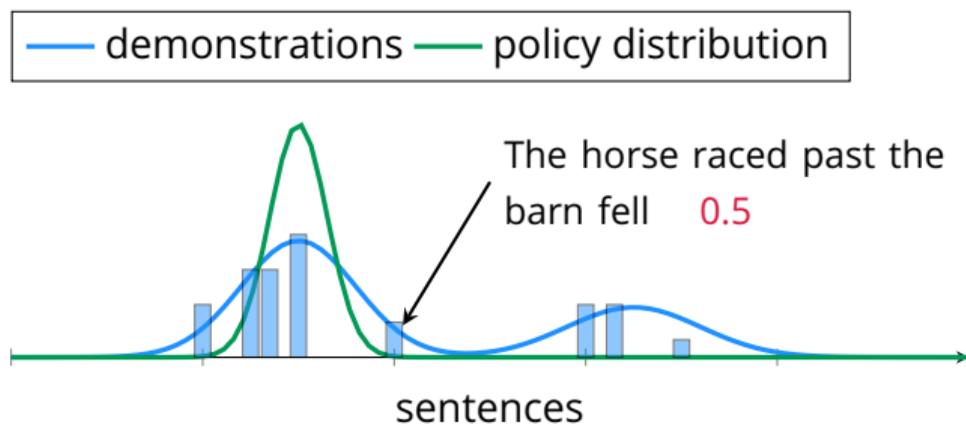
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$$\nabla_{\theta} J(\theta) = \mathbb{E}_{\pi_{\theta}} \left[\sum_t \nabla_{\theta} \log \pi_{\theta}(a_t | s_t) \hat{Q}(s_t, a_t) \right]$$

Offline policy gradient

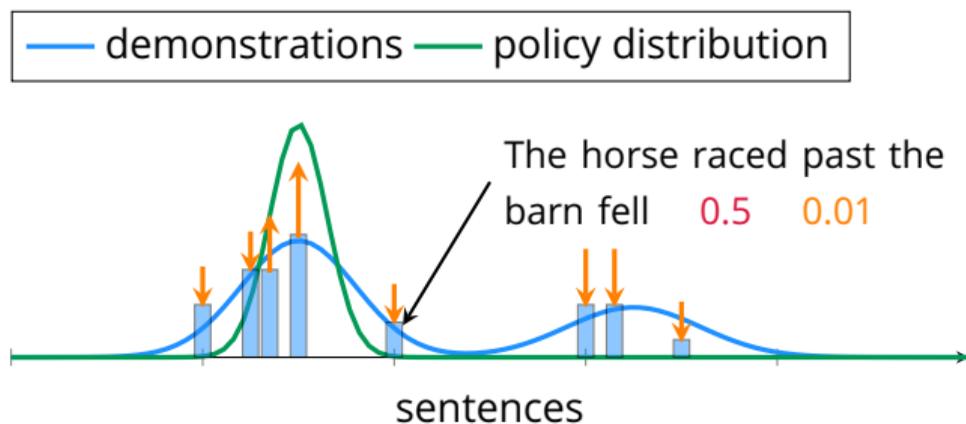
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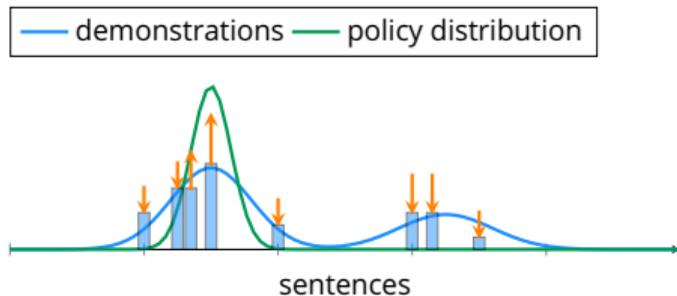
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Objective: $\mathbb{E}_{\pi_{\theta}} [R(s, a)]$



$$\nabla_{\theta} J(\theta) = \mathbb{E}_{\pi_D} \left[\sum_t w_t \nabla_{\theta} \log \pi_{\theta}(a_t | s_t) \hat{Q}(s_t, a_t) \right]$$

Approximated importance weights



$$w_t = \pi_{\theta}(a_t | s_t)$$

- ▶ **Intuition:** up-weight actions preferred by the current policy
- ▶ Closer to model distribution

What is a good reward function

Offline policy gradient: $\sum_{t'=t}^T R(s_{t'}, a_{t'})$

$$\nabla_{\theta} J(\theta) \approx \mathbb{E}_{\pi_D} \left[\sum_t \pi_{\theta}(a_t | s_t) \nabla_{\theta} \log \pi_{\theta}(a_t | s_t) \hat{Q}(s_t, a_t) \right]$$

- ▶ Finding a good R is hard in general (the evaluation problem).
- ▶ But we only need to score the **demonstrations**.

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| | naive |
|------------------------------------|-------|
| The horse fell | 1 |
| The horse was in the barn | 1 |
| The horse raced past the barn fell | 1 |

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| | naive | ideal ($R = \log p_{\text{human}}$) |
|------------------------------------|-------|---------------------------------------|
| The horse fell | 1 | 0.5 |
| The horse was in the barn | 1 | 0.2 |
| The horse raced past the barn fell | 1 | 0.1 |

Estimate p_{human} (for the demonstrations)

$$R_{\text{ideal}} = \log p_{\text{human}}$$

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Approximate p_{human} using the demonstrations:

$$\hat{p}_{\text{human}} \stackrel{\text{def}}{=} \min_q \text{KL}(\pi_D \| q) = p_{\text{MLE}}$$

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Reward functions:

1. **Product** of \hat{p}_{human} : a sequence is good if *all* words are good.

$$\hat{Q}(s_t, a_t) = \sum_{t'=t}^T \log \hat{p}_{\text{human}}(a_{t'} | s_{t'})$$

2. **Sum** of \hat{p}_{human} : a sequence is good if *most* words are good.

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- ▶ Up-weight examples with **high probability under p_{MLE}** .

Experiment setup

Datasets:

- ▶ Question generation (NQG) [Zhou+ 2017]

Input: Some members of this community emigrated to the United States in the 1980s .

Output: In what era did some members of this community emigrate to the US ?

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Variations of GOLD:

- ▶ GOLD- p : product of \hat{p}_{human}
- ▶ GOLD- s : sum of \hat{p}_{human}

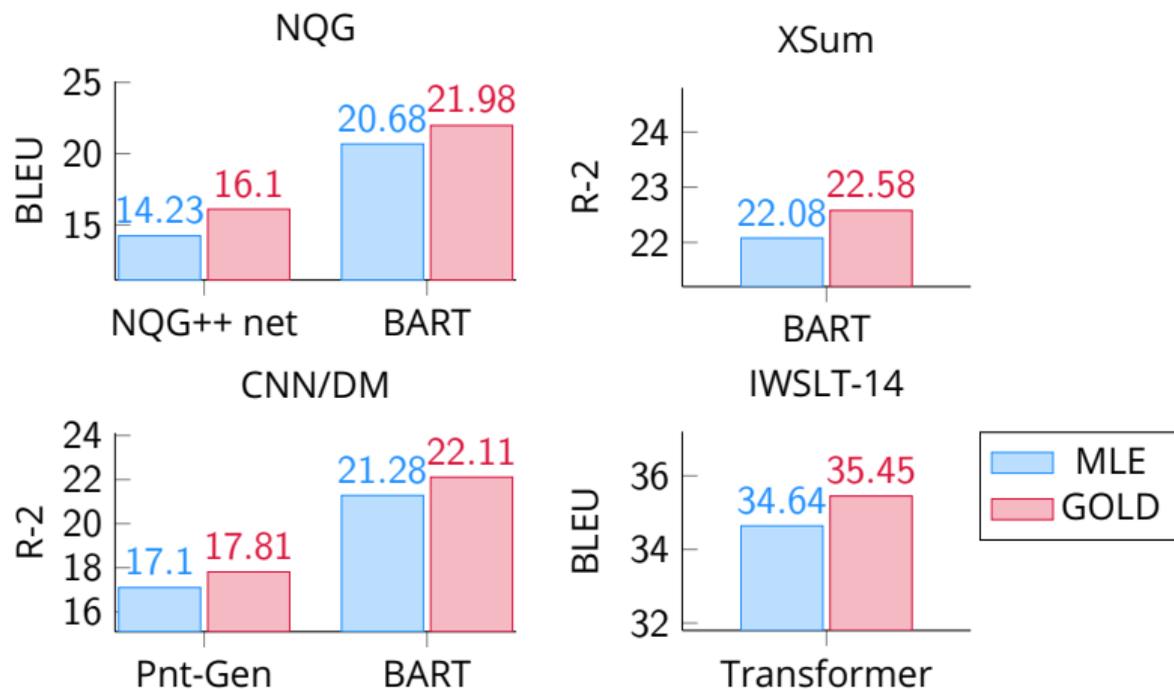
Characteristics of GOLD

- GOLD improves generation quality
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GOLD on standard vs advanced models



GOLD improve both standard and Transformer-based models.

Human evaluation

Human comparison on 200 pairs of outputs:

- ▶ Question generation

Which question is better given the paragraph and the intended answer?

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Which summary is closer to the reference in meaning?

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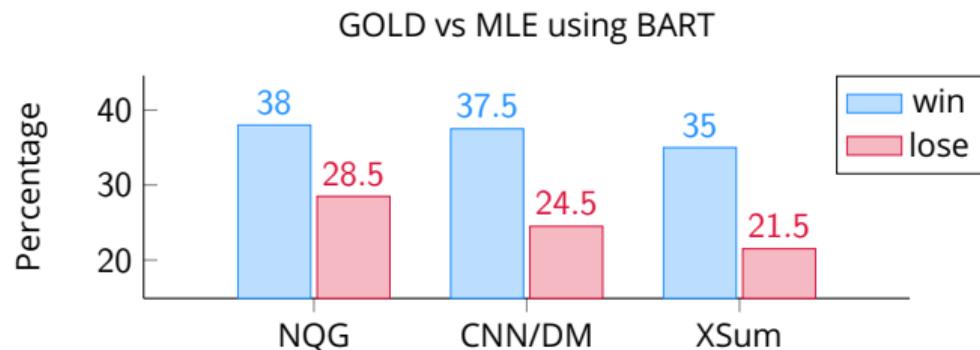
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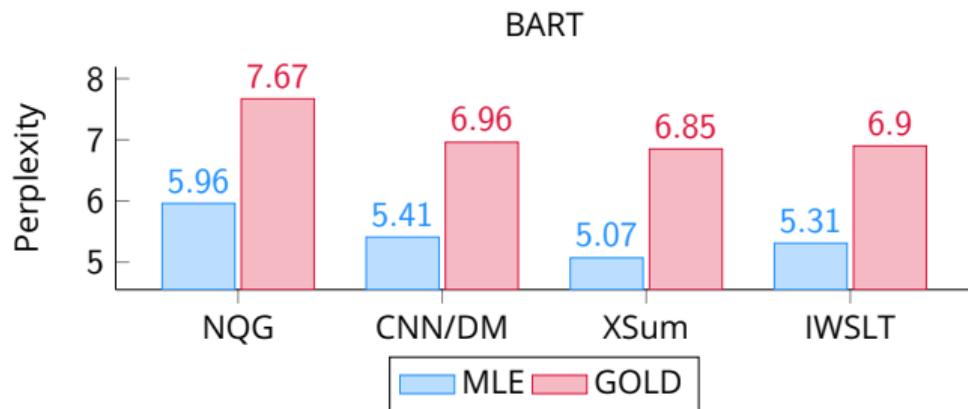
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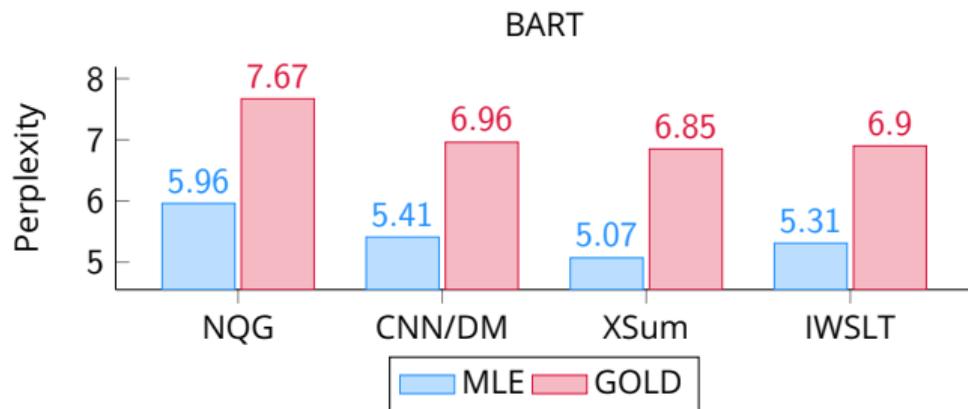
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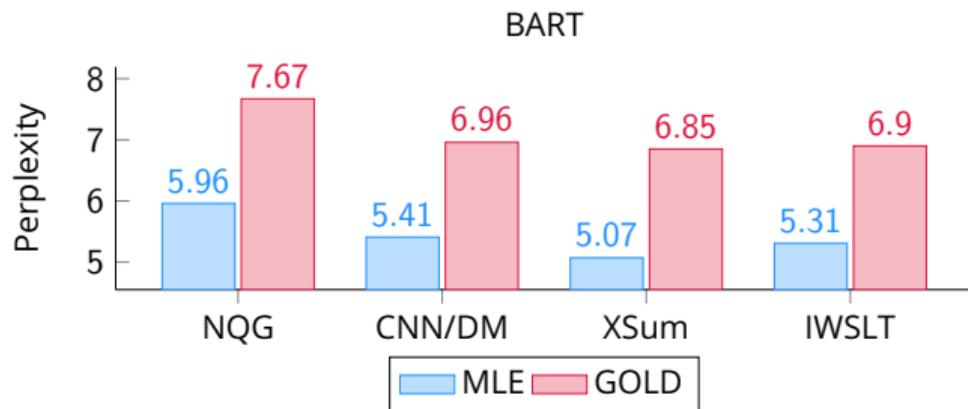
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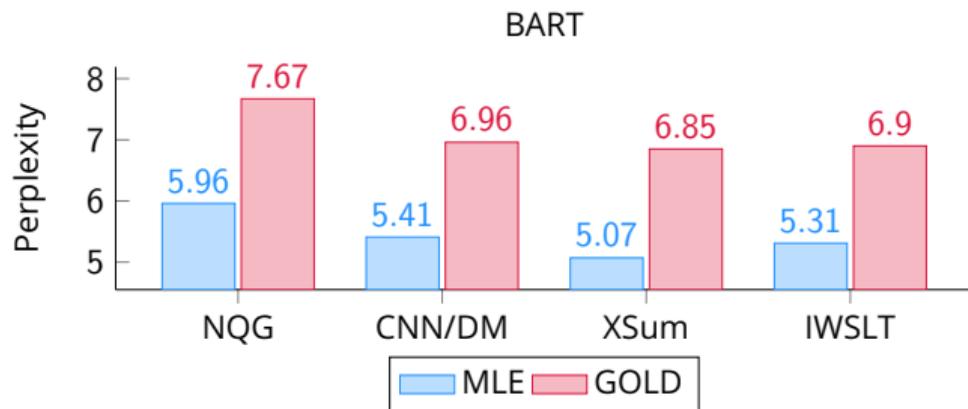


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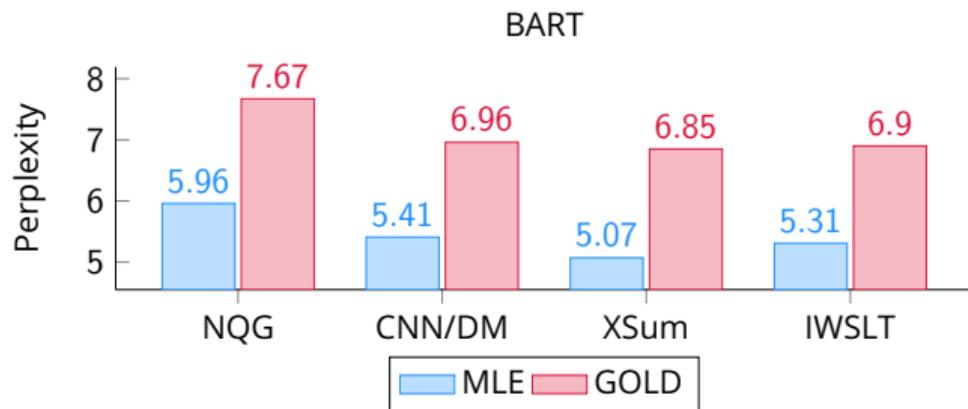
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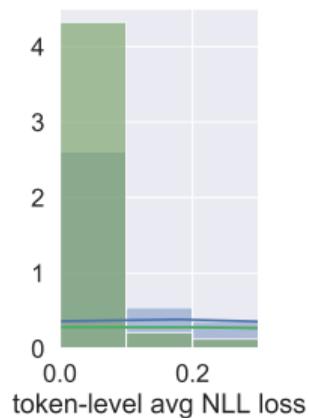
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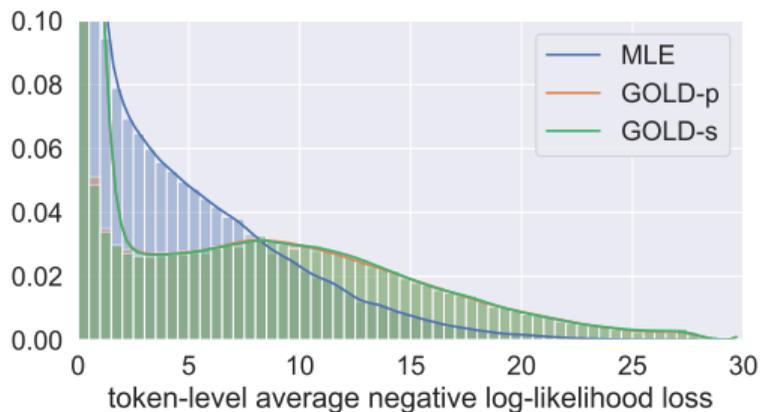


- ▶ High perplexity \neq low quality
- ▶ GOLD improves quality at the cost of diversity (recall)
- ▶ Using better models alleviate the quality-diversity tradeoff
(NQG++ net ppl: GOLD/158 vs MLE/29)

High perplexity but good BLEU/ROUGE score?



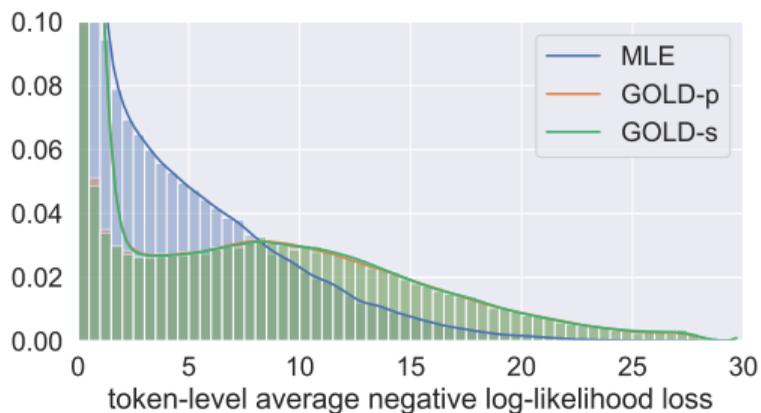
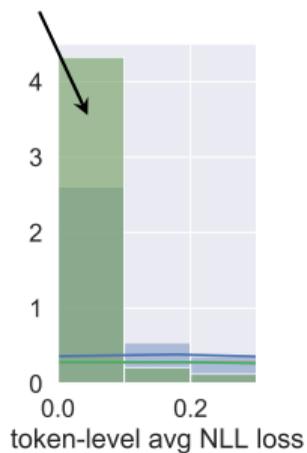
NQG dev set



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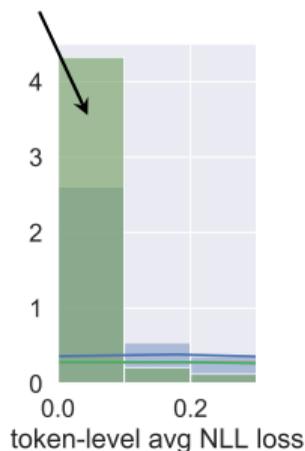
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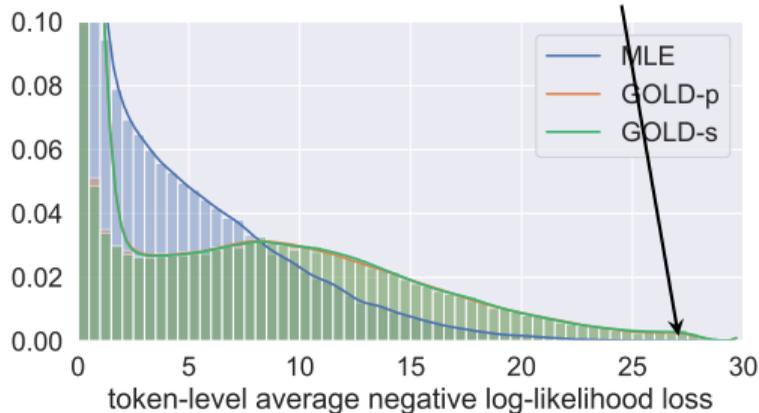


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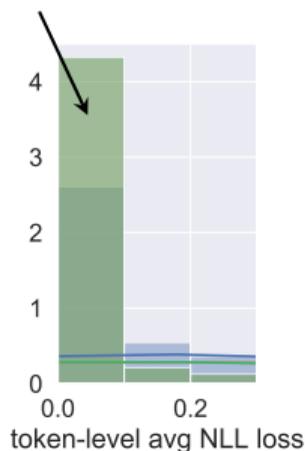


GOLD has a longer tail of high loss tokens

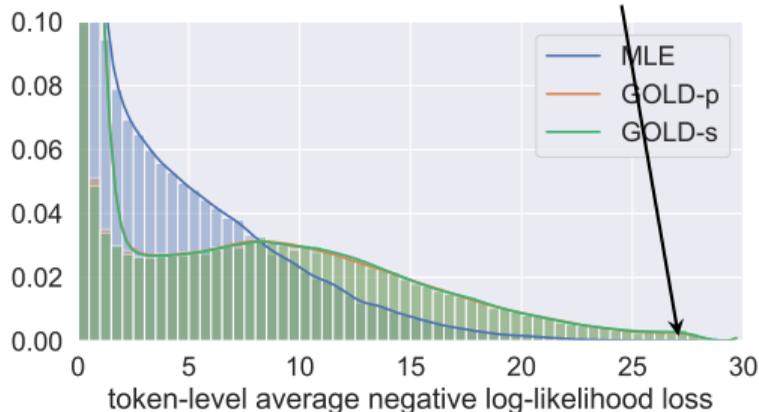
- ▶ Perplexity is sensitive to (a few) low probability tokens

High perplexity but good BLEU/ROUGE score?

GOLD is skewed towards near-zero losses

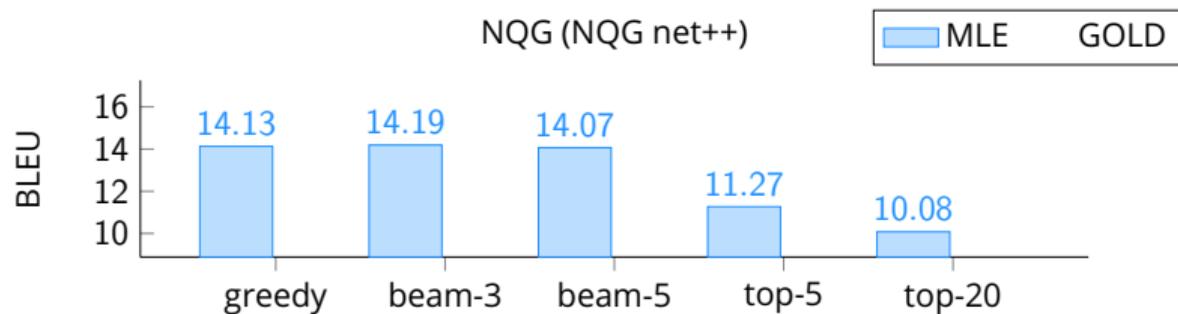


NQG dev set

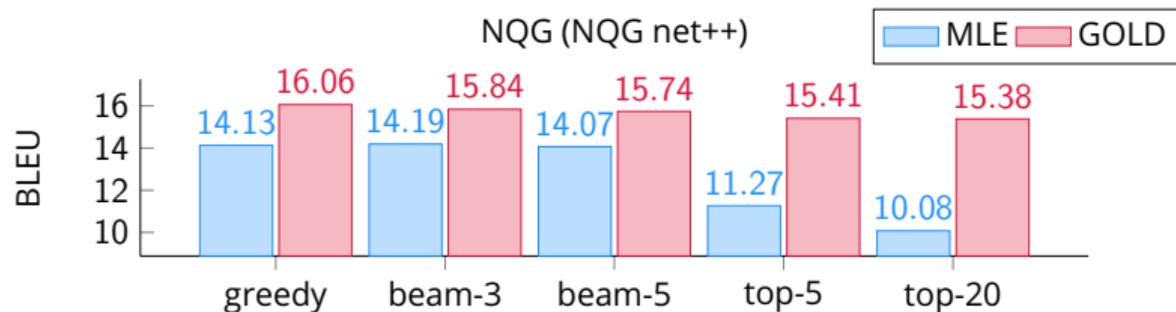


- ▶ Perplexity is sensitive to (a few) low probability tokens
- ▶ GOLD improves quality (precision) at the cost of diversity (recall)

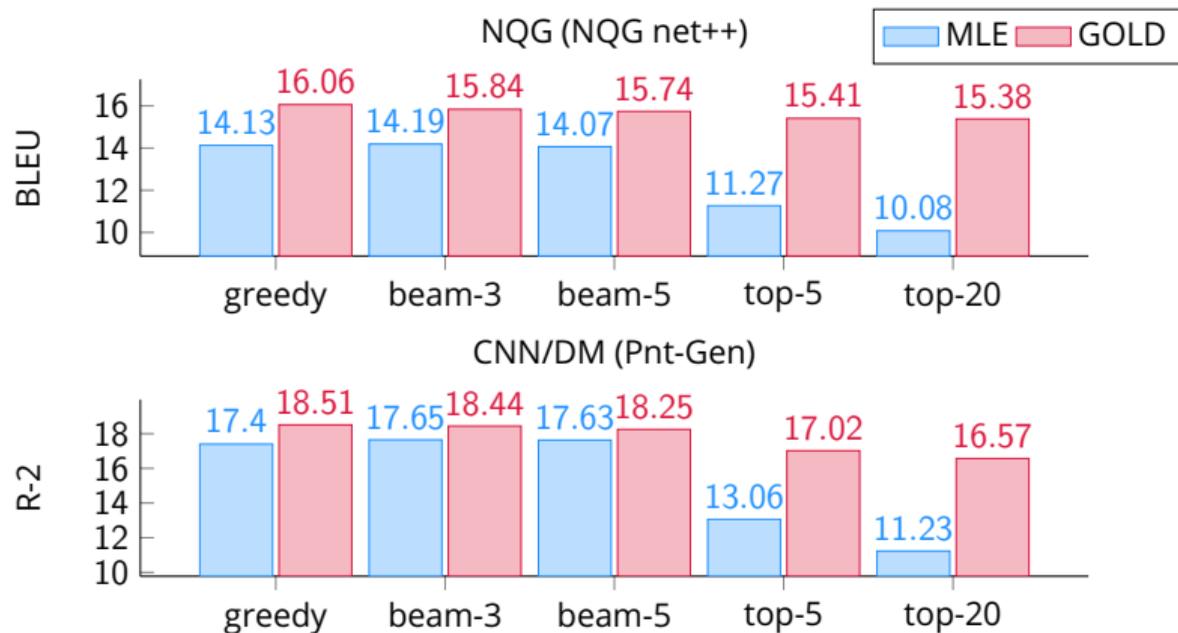
Low sensitivity to decoding algorithms



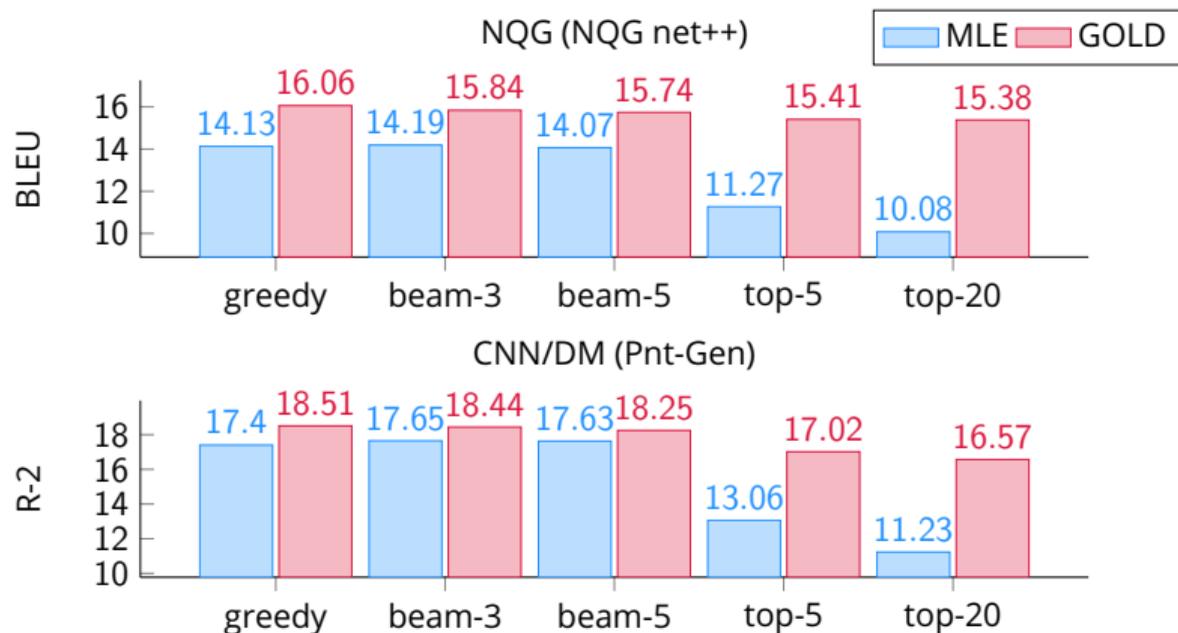
Low sensitivity to decoding algorithms



Low sensitivity to decoding algorithms



Low sensitivity to decoding algorithms



- ▶ High-precision models are less sensitive to decoding algorithms
- ▶ Greedy decoding works just fine

Characteristics of GOLD

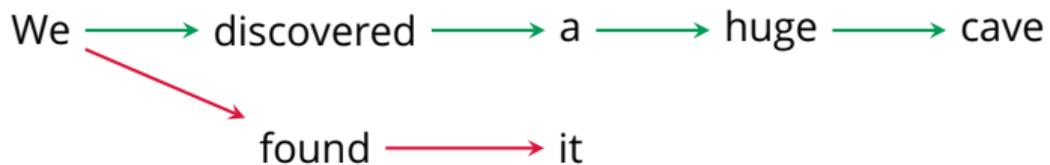
- ✓ GOLD improves generation quality
 - ▶ Better quality in terms of automatic metric and human judgment
- ✓ GOLD improves precision at the cost of recall
 - ▶ On reference: more low-ppl tokens with a long tail of high-ppl tokens
 - ▶ Generation: less sensitive to decoding algorithms
- GOLD alleviates exposure bias

Characteristics of GOLD

- ✓ GOLD improves generation quality
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- **GOLD alleviates exposure bias**

Exposure bias

Mismatched training and inference prefix:



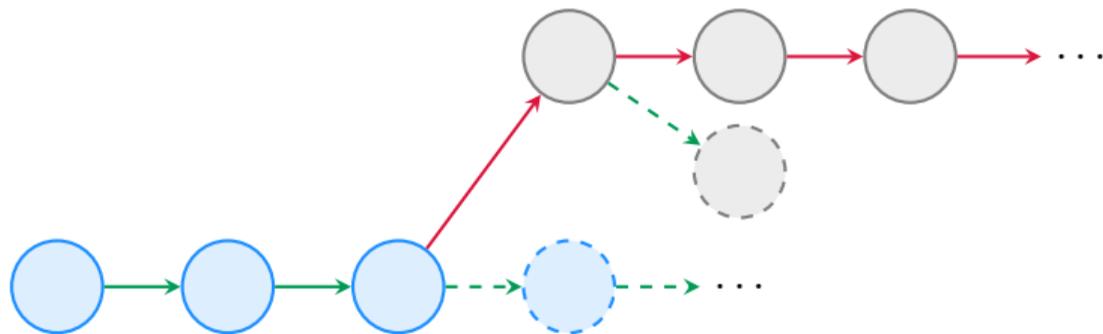
Training $p(t\text{-th word} \mid \text{gold prefix, context})$

Inference $p(t\text{-th word} \mid \text{generated prefix, context})$

Exposure bias

Theoretical worst case:

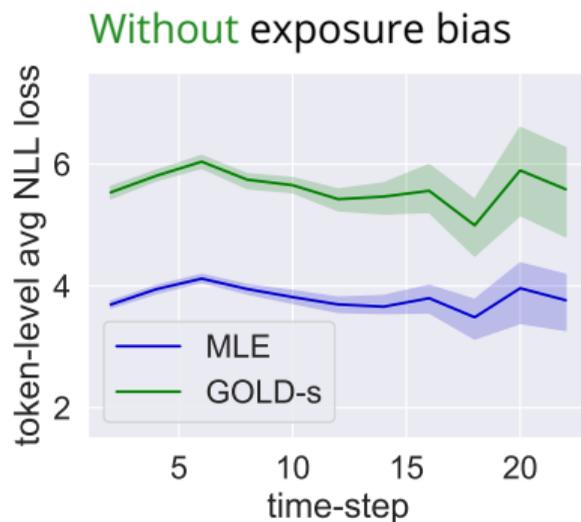
$O(\text{\#steps}^2)$ mistakes [Ross+ 2011]



Once off the **gold path**, a **mistake** is made in *all* following steps.

GOLD alleviates exposure bias

GOLD alleviates exposure bias

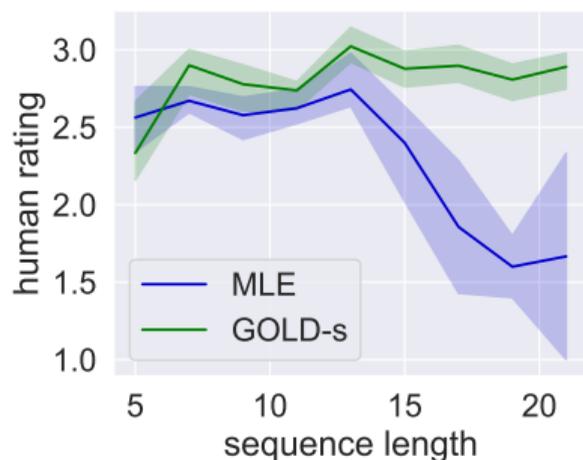


- ▶ Given reference prefix, both losses do not change with length

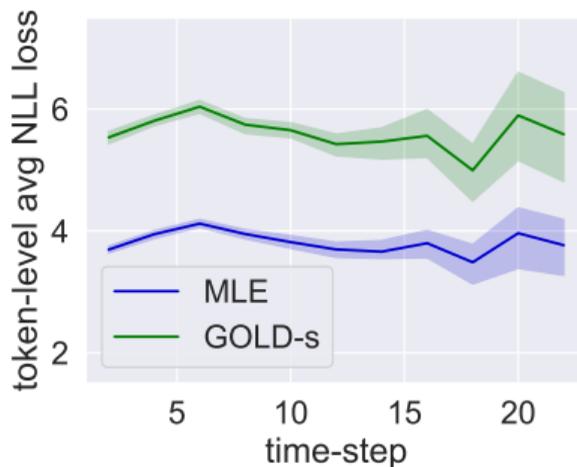
GOLD alleviates exposure bias

NQG (NQG net++)

With exposure bias



Without exposure bias



- ▶ Given reference prefix, both losses do not change with length
- ▶ Given generated prefix, MLE outputs degrade with length while GOLD outputs is stable

Characteristics of GOLD

- ✓ GOLD improves generation quality
 - ▶ Better quality in terms of automatic metric and human judgment
- ✓ GOLD improves precision at the cost of recall
- ✓ GOLD alleviates exposure bias
 - ▶ Generation quality is stable across output lengths.

Contents

When to use GOLD?

When it's good enough to have one good answer (high precision)

- ▶ Machine translation
- ▶ Summarization
- ▶ Code generation

Not suitable when multiple diverse answers are desired (high recall)

- ▶ Creative writing assistant
- ▶ Story generation

Close the gap



$$\mathbb{E}_{\pi_D} [\log \pi_{\theta}(x)] \quad (\text{MLE})$$



$$\mathbb{E}_{\pi_{\theta}} [\log p_{\text{human}}(x)]$$

Close the gap



$$\mathbb{E}_{\pi_D} [\log \pi_{\theta}(x)] \quad (\text{MLE})$$



$$\mathbb{E}_{\pi_D} [\pi_{\theta}(x) Q(x)] \quad (\text{GOLD})$$



$$\mathbb{E}_{\pi_{\theta}} [\log p_{\text{human}}(x)]$$

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- ▶ Interact with the environment
- ▶ Robust reward functions

Close the gap



$$\mathbb{E}_{\pi_D} [\log \pi_{\theta}(x)] \quad (\text{MLE})$$



$$\mathbb{E}_{\pi_D} [\pi_{\theta}(x) Q(x)] \quad (\text{GOLD})$$

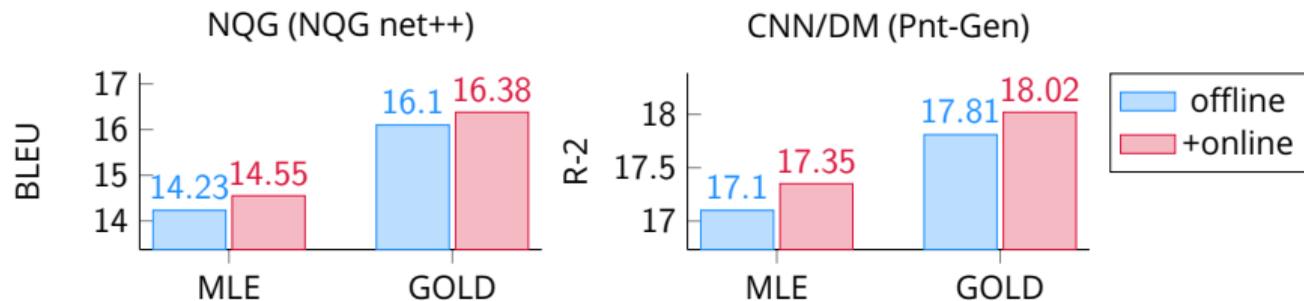


$$\mathbb{E}_{\pi_{\theta}} [\log p_{\text{human}}(x)]$$



- ▶ Interact with the environment (RL algorithms)
- ▶ Robust reward functions (**key challenge**)

Averaging over model distribution: additional interaction



- ▶ Additional on-policy training yields *marginal* improvement
- ▶ Reward function may not be useful on model outputs

Better reward function: human in the loop

Failed attempt:

- ▶ Learn a reward function from human-annotated translations
- ▶ Use the reward function in online/offline RL
- ▶ Only helpful with small data

Pitfall with learned reward function:

- ▶ Model can exploit shortcuts in the learned reward model, e.g., length, specific phrases

RL for alignment

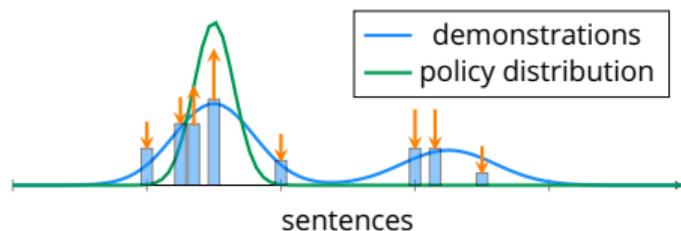
Learning from human preferences using PPO:

- ▶ Training a Helpful and Harmless Assistant with Reinforcement Learning from Human Feedback. Anthropic.
- ▶ Aligning Language Models to Follow Instructions. OpenAI.

What made it work?

- ▶ Periodically update the preference function
- ▶ Quality control (reward signal from human can be sparse and noisy)

Parting remarks



- ▶ RL is a great framework for **aligning task objective and learning objective**
- ▶ Offline RL helps with **scaling** (reducing to supervised learning)
- ▶ For text generation, the key is to find the **right reward function**.
 - ▶ How to best represent human preference which can be ambiguous?